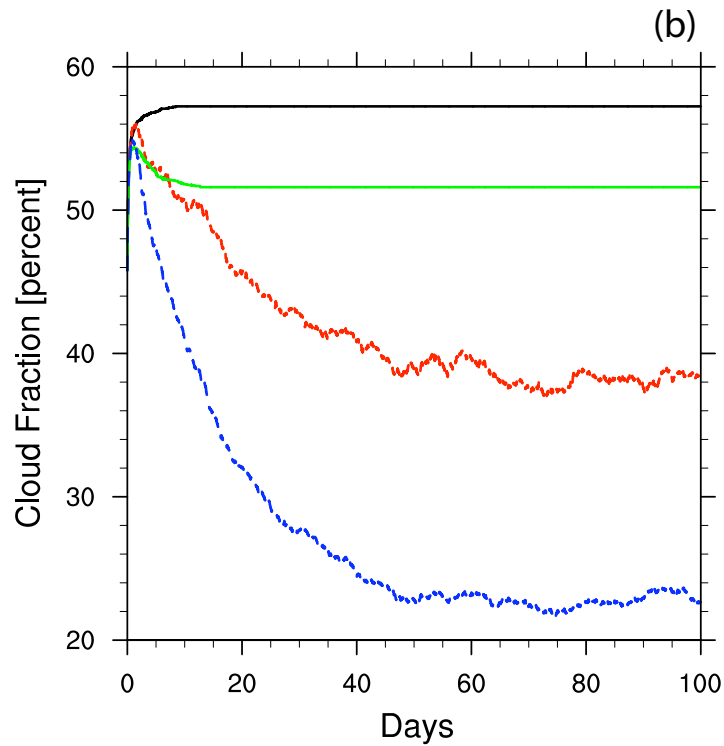


Random initial cloud depth



black: control-run

green: inter-run

red: noise-run

blue: both-run

